

# Modelling of damage in impact of composite structures using higherorder elements

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### Overview



Impact modelling

Modelling of sublaminates with solid continuum elements C<sup>1</sup> continuity

Implementation Explicit time integration in LS-Dyna

> Verification examples Rigid body impact



Rotation enabled cohesive and continuum elements C<sup>1</sup> continuity

 Corner nodes of cohesive element with rotations Adaptive initiation of cohesive elements between sublaminates

Higher order AMS [1]

[1] Jagan Selvaraj, Supratik Mukhopadhyay, Luiz F. Kawashita, Stephen R. Hallett, Modelling delaminations using adaptive cohesive segments with rotations in dynamic explicit analysis, Engineering Fracture Mechanics, Volume 245, 2021, 107571, ISSN 0013-7944, https://doi.org/10.1016/j.engfracmech.2021.107571.





## **Continuum and Cohesive element**



Continuum model + Cohesive zone modelling (CZM)

 Meshing Burden - Need to predefine cohesive elements in a mesh.



Adaptive modelling of cracks Adaptive Mesh Segmentation (AMS)



- CZM linear elements require fine mesh
- High computational cost
- Large linear meshes introduce discretisation errors

Higher order cohesive segments

Higher order AMS

An integrated approach to solve problems in damage modelling

• Demonstrated with impact modelling cases





#### Higher order AMS



#### Discretisation using coarser meshes



• Corner nodes of cohesive element with rotations

Rotation enriched cohesive elements

Higher order

Jagan Selvaraj, Luiz F. Kawashita, Mehdi Yasaee, Gordon Kalwak, Stephen R. Hallett, Soft body impact on composites: Delamination experiments and advanced numerical modelling, Composites Science and Technology, Volume 208, 2021, 108777, ISSN 0266-3538, https://doi.org/10.1016/j.compscitech.2021.108777.





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#### **Double Cantilever Beam**



- Ability to add multiple integration points within cohesive segments.
- Numerically accurate modelling with Higher Order AMS using 1 mm mesh.
- Discretisation using larger meshes Linear elements require 0.25 mm mesh.
- 50% less CPU time for similar accuracy when compared to linear elements with same implementation.







#### Soft Body Beam Bending Impact









# Ply-scale semidiscrete crack modelling

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,  $\sigma_N$ 

#### **Damage Initiation**

Matrix in Compression

Based on Mohr-Coulomb theory

 $\left(\frac{\tau_L}{S_L - \mu_L \sigma_N}\right)^2 + \left(\frac{\tau_T}{S_T - \mu_T \sigma_N}\right)^2 = 1$ 

 $S_L$  - Longitudinal shear strength;  $S_T$  - Transverse shear strength  $\mu_L$ ,  $\mu_T$  - longitudinal and transverse friction coefficients  $\tau_L$ ,  $\tau_T$  - longitudinal and transverse shear stress

$$S_T = \frac{Y_c}{2\tan\varphi_0} \qquad \mu_T = -\frac{Y_c}{\tan 2\varphi_0} \qquad \mu_L = S_L \frac{\mu_T}{S_T}$$

Matrix in Tension

$$\left(\frac{\sigma_N}{S_T}\right)^2 + \left(\frac{\tau_L}{S_L}\right)^2 + \left(\frac{\tau_T}{S_T}\right)^2 + \lambda \left(\frac{\sigma_N}{S_T}\right) \left(\frac{\tau_L}{S_L}\right) + \kappa \left(\frac{\sigma_N}{S_T}\right) = 1$$

1-2-3 Material Frame

 $Y_T$  - Transverse tensile strength;  $Y_C$  - Transverse compressive strength  $\lambda$  and  $\kappa$  are based on in-situ tensile strength and longitudinal friction co-efficient





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 $\tau_T$ 

 $\tau_L$ 

#### **Damage Evolution**

Using a equivalent mixed-mode driving stress from a quadratic stress calculation

$$\sigma_m = \sqrt{\sigma_N^2 + \tau_T^2 + \tau_L^2}$$

Similarly, driving strain  $\varepsilon_m$  can be calculated

Damage variable

$$d_m = \frac{\varepsilon_m^f(\varepsilon_m - \varepsilon_m^0)}{\varepsilon_m(\varepsilon_m^f - \varepsilon_m^0)}$$

$$arepsilon_m^f$$
 - strain at failure;  $arepsilon_m^0$  - strain at initiation

 $G_c$  - mixed mode fracture energy

$$\varepsilon_m^f = \frac{2 \ G_c}{\sigma_m^0 l_e}$$

 $l_{e}$  - characteristic length; taken as cubic root of the volume

In directed CDM exact length is used









#### Open-hole tensile test

Ply-scale discrete crack modelling [1]



Ply-scale semi-discrete crack modelling





[1] Jagan Selvaraj, Luiz F. Kawashita, Stephen R. Hallett, Mesh independent modelling of tensile failure in laminates using mixed-time integration in explicit analysis, Engineering Fracture Mechanics, Volume 259, 2022, 108113, ISSN 0013-7944







# Sublaminate scale semi-discrete crack modelling

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#### Sublaminate Modelling



- Eliminates the ply-level discretisation requirement.
- Aimed at modelling global damage behaviour.
- Performed without directed CDM





## Damage variable

• Strain in the plies of the sublaminate are assumed to be same.

Strain in global frameRotationStrain in material frameof the sublaminatetensorof the ply

• Check for damage initiation and application of damage evolution with a damage variable.

$$\sigma_{22} \leftarrow (1 - D) \sigma_{22}$$
  

$$\sigma_{12} \leftarrow (1 - D) \sigma_{12}$$
  

$$\sigma_{23} \leftarrow (1 - D) \sigma_{23}$$
Ply-level stress

• Stress in the sublaminate is calculated with a weighted average of ply-level stress



Sublaminate modelled by a continuum element



Distribution of plies within a sublaminate

Damage is calculated for each ply







X.C. Sun, S.R. Hallett, Barely visible impact damage in scaled composite laminates: Experiments and numerical simulations, International Journal of Impact Engineering, Volume 109, 2017, Pages 178-195.





#### Reference – Sun & Hallett

- Ply level model; 32 individual plies are modelled
- Linear solid elements 290,480 elements
- Cohesive elements (Delamination + embedded matrix cracks) 2,907,624 elements

#### Higher order AMS

- Sublaminate model; 8 sublaminates (one element per sublaminate)
- Rotation enabled elements 120,000 elements (~ 60 % less)
- Delamination Cohesive elements 'on-the-fly'
- Matrix cracks Sublaminate damage modelling









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	In-plane mesh size (mm)	No. of elements per sublaminate through the thickness	Delamination diameter (mm)	No. of DOFs	Time step (s)	Run-time (hours)
Linear formulation (Reduced integration)	0.5	3	37.0	3,773,173	1.21 x 10 <sup>-5</sup>	54
	1.0	3	24.0	1,143,875	1.21 x 10 <sup>-5</sup>	35
Linear formulation (Full integration)	0.5	3	36.0	3,773,173	1.21 x 10 <sup>-5</sup>	151
	1.0	3	25.0	1,143,875	1.21 x 10 <sup>-5</sup>	94
Higher-order AMS	1.0	1	41.0	326,238	3.05 x 10 <sup>-5</sup>	20
	1.5	1	41.0	169,830	3.05 x 10 <sup>-5</sup>	15





### High velocity impact



Hao Cui, Daniel Thomson, Sina Eskandari, Nik Petrinic, A critical study on impact damage simulation of IM7/8552 composite laminate plate, International Journal of Impact Engineering, Volume 127, 2019, Pages 100-109.





### High velocity impact – 59 m/s

Ply-level damage modelling using CDM for intra and interlaminar damage

Sublaminate-scale damage modelling using CDM for intralaminar damage and adaptively initiated cohesive elements for delamination







### High velocity impact – 106 m/s







### High velocity impact

- Accurate modelling of stiffness and the residual velocity is obtained with the proposed method.
- Ability to model at sublaminate-scale is essential in modelling large structures.
- Higher-order elements are therefore beneficial at larger length scales and mesh sizes

	No. of DOFs	Thickness direction mesh (mm)	In-plane mesh (mm)
Ply-level modelling	4,848,120	0.125	1.0
Sublaminate-scale Higher Order AMS	1,185,096	1.0	1.5





#### Summary

- An adaptive damage modelling method using higher order continuum and cohesive elements are introduced.
- This method is semi-discrete; delamination is modelled using cohesive elements and in-plane damage using continuum damage mechanics.
- Verification of the method is performed using impact modelling examples.
- The method successfully models global damage behaviour and is computationally efficient.





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# Thank you

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