

TRANSVERSE LIQUID COMPOSITE MOULDING: DEVELOPMENT AND COMPARISON OF PROCESS MODELS

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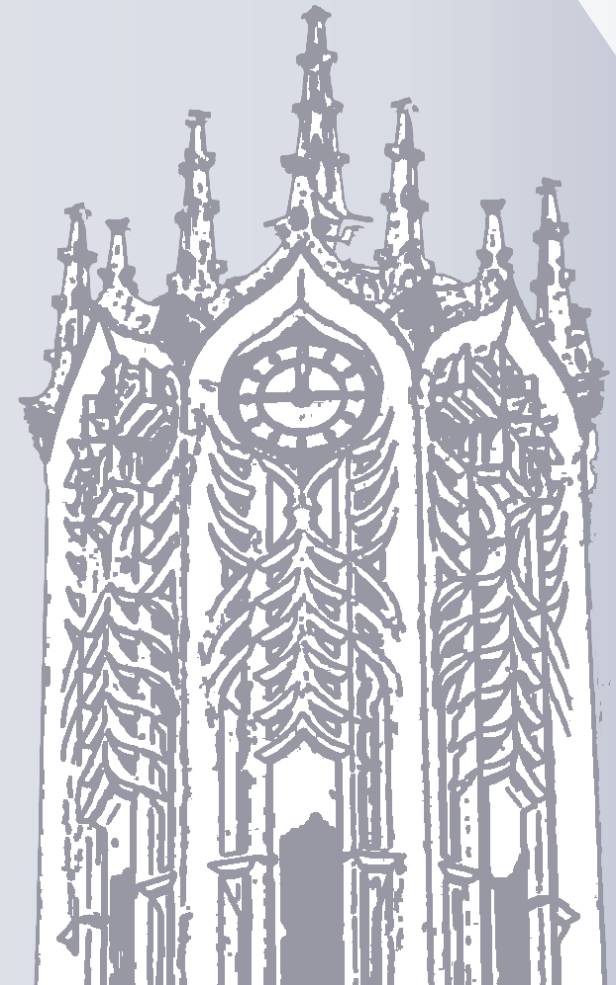
³ Centre for Advanced Materials Manufacturing and Design, University of Auckland, New Zealand



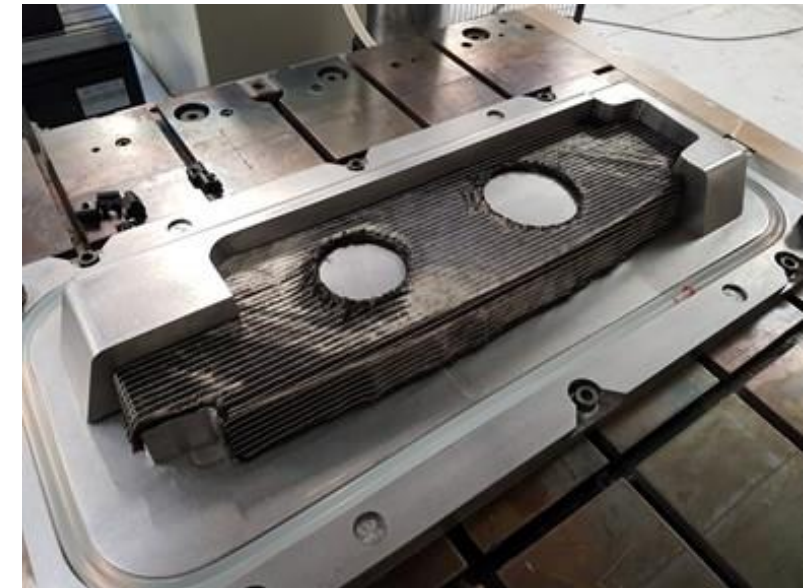
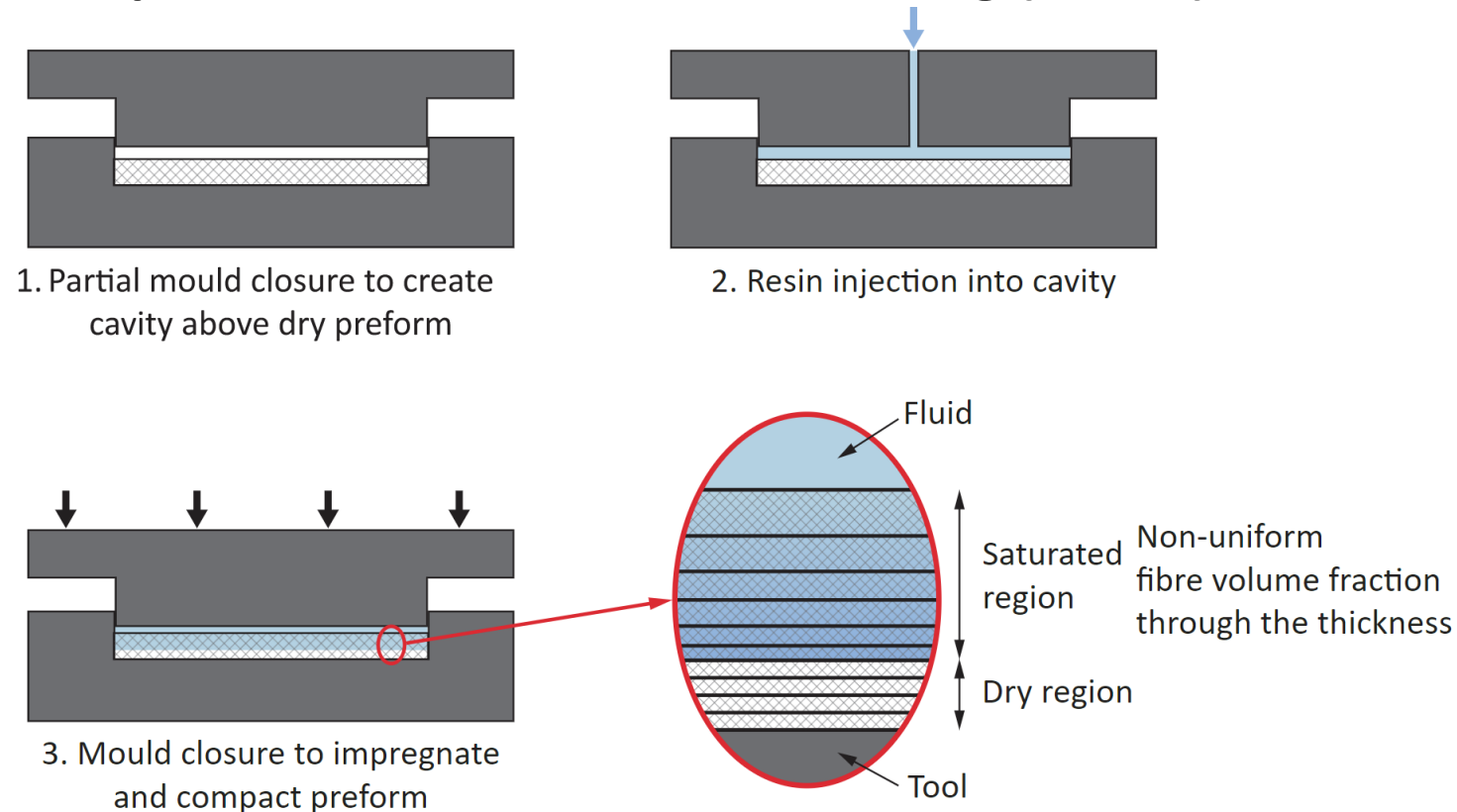
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CENTRE FOR ADVANCED MATERIALS
MANUFACTURING & DESIGN

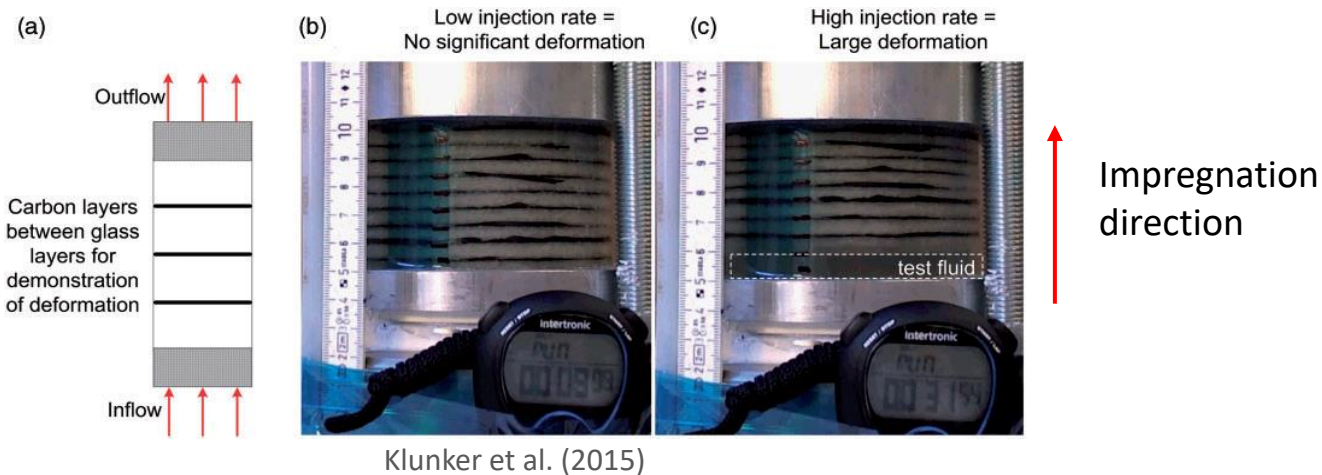


- Liquid Composite Moulding: impregnation of a dry preform with liquid resin in a mould
- Impregnation in the through-thickness (transverse) direction \Rightarrow reduce the flow length
- **Compression Resin Transfer Moulding (CRTM)**



Aircraft wing rib preform for CRTM

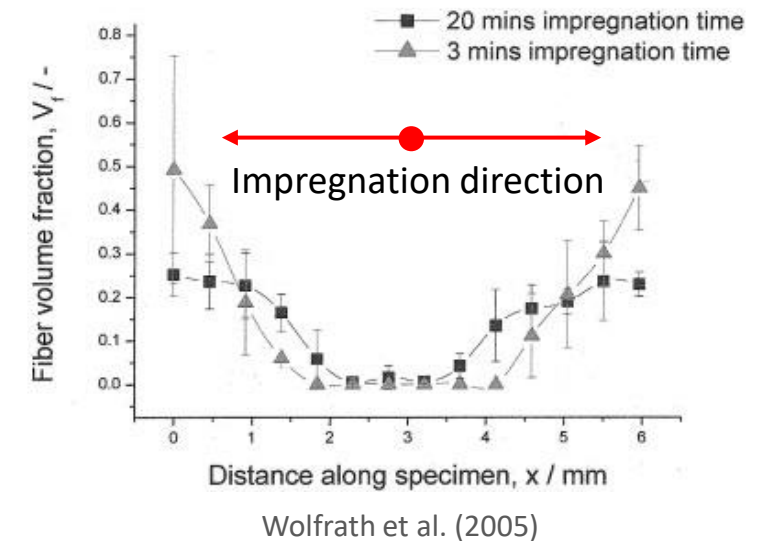
- Examples of non-uniform compaction during through thickness impregnation
Increasing fibre volume fraction in the impregnation direction



Impregnation
direction



Studer et al. (2019)

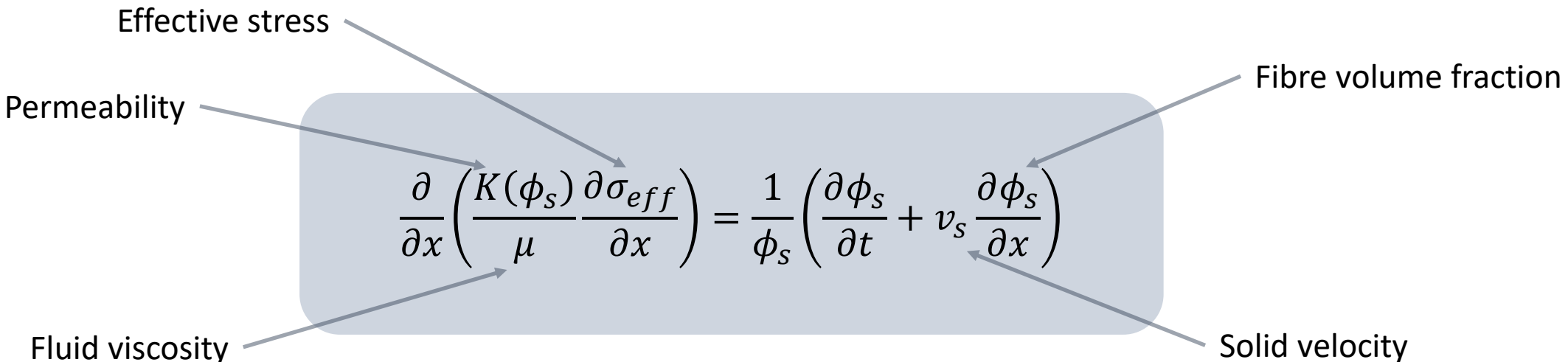


- **Non-uniform fibre volume fraction** in the final part can lead to inconsistent structural properties
- Simulate the resin flow and preform deformation to predict the **homogenisation time** and **tooling forces** for transverse LCM processes
- Many process models have been developed which make various simplifying assumptions to reduce computational cost and model complexity

Aims

- Compare transverse LCM process models with varying model complexity
- Investigate manufacturing conditions that result in accurate predictions for these process models

- Conservation of mass (fluid and solid)
- Darcy's law for flow through porous media
- Terzaghi's law: total applied stress = effective stress + fluid pressure, $\frac{\partial p}{\partial x} + \frac{\partial \sigma_{eff}}{\partial x} = 0$
- Constitutive relation for permeability $K(\phi_s)$
- Constitutive relation for compaction stress $\sigma_{eff}^{wet}(\phi_s), \sigma_{eff}^{dry}(\phi_s)$

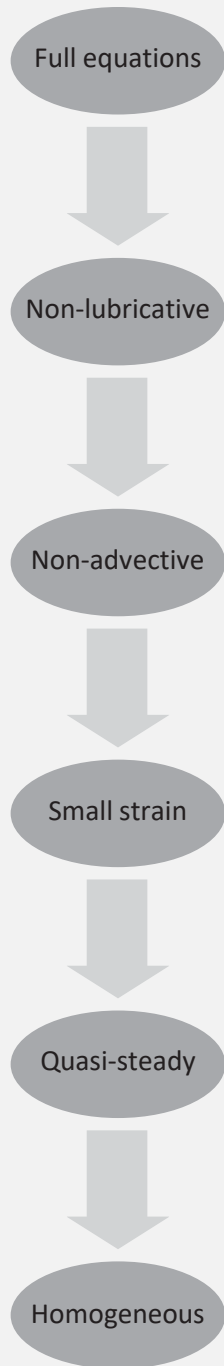

$$\frac{\partial}{\partial x} \left(\frac{K(\phi_s)}{\mu} \frac{\partial \sigma_{eff}}{\partial x} \right) = \frac{1}{\phi_s} \left(\frac{\partial \phi_s}{\partial t} + v_s \frac{\partial \phi_s}{\partial x} \right)$$

Labels and arrows:

- Effective stress: points to σ_{eff}
- Permeability: points to $K(\phi_s)$
- Fluid viscosity: points to μ
- Fibre volume fraction: points to ϕ_s
- Solid velocity: points to v_s

Simplified process models

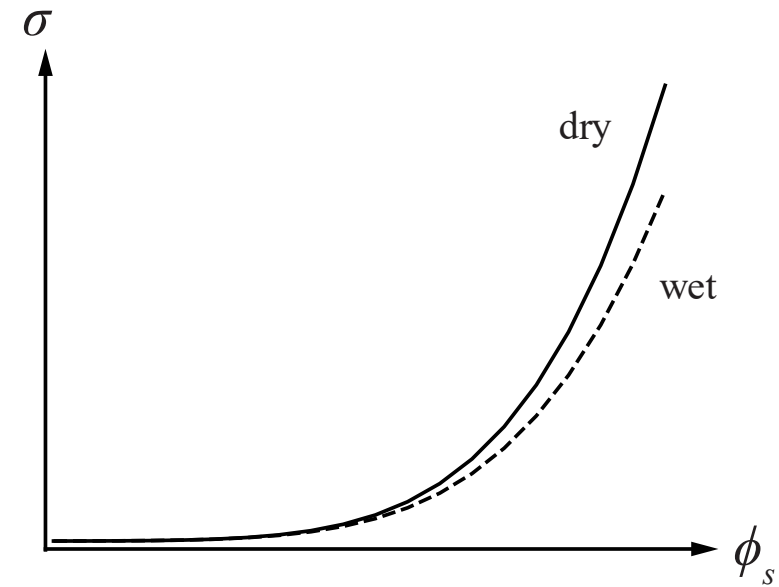
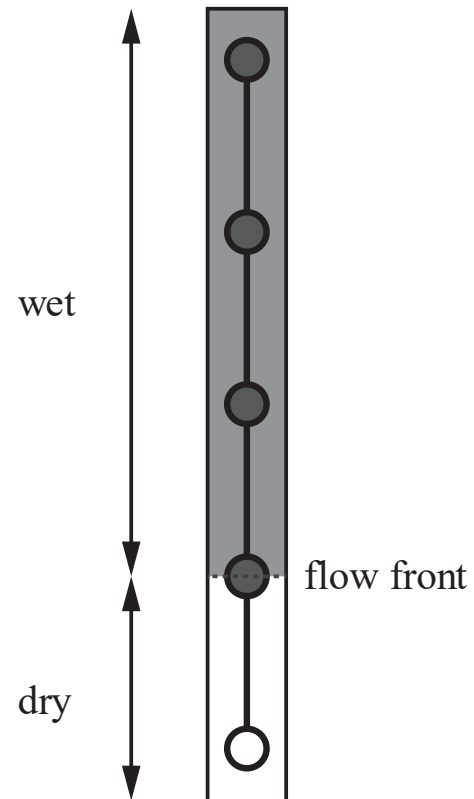
Simplifications to the governing equation



Decreasing
model
complexity

- Previous studies have made assumptions to simplify the full governing equation to reduce computational cost and model complexity
- Many simplified models are based on the assumption of relatively slow flow and small deformations

Non-lubricative assumption



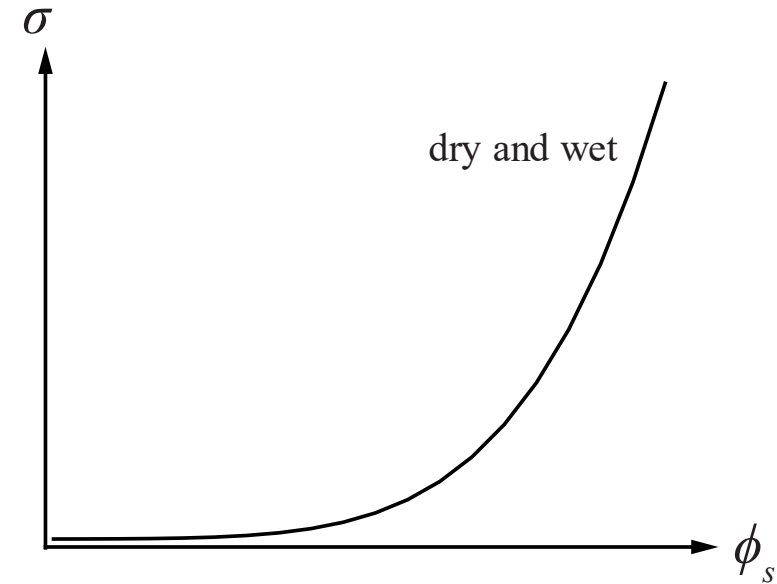
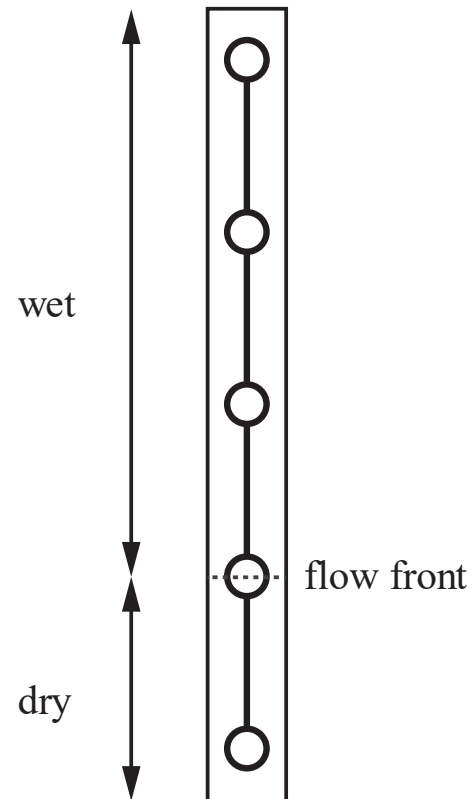
Full equations

Identical wet & dry
compaction behaviour

Non-lubricative

Non-lubricative assumption

- Assume negligible lubrication effects



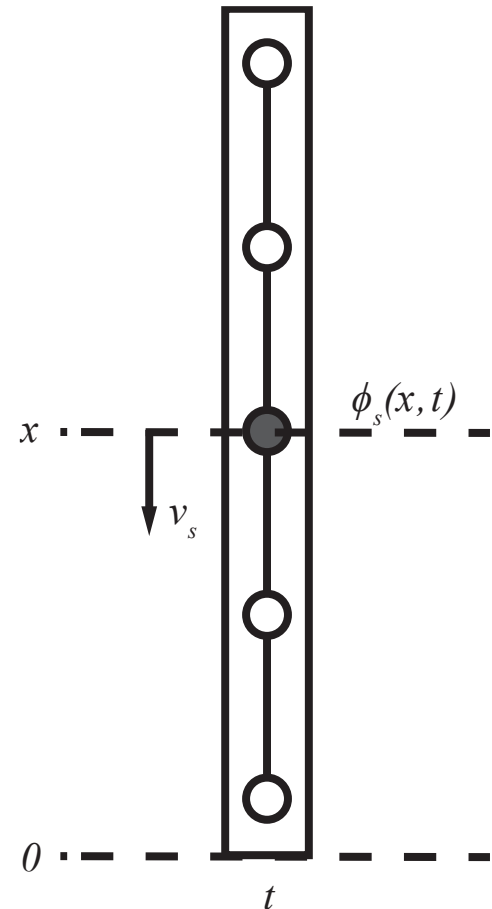
Full equations

Identical wet & dry
compaction behaviour

Non-lubricative

Non-advective assumption

- The time derivative of ϕ_s must include the change in ϕ_s due to the **movement of the solid**, as well as the change in ϕ_s at x .
- At time t :



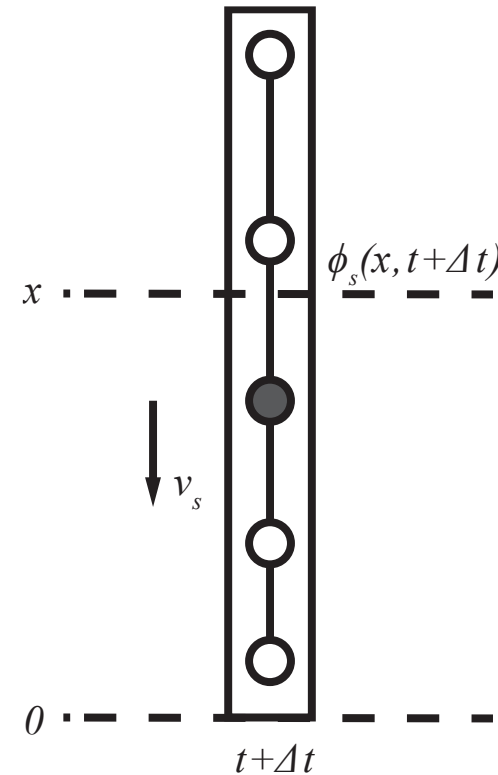
Full equations

Identical wet & dry
compaction behaviour

Non-lubricative

Non-advective assumption

- At time $t + \Delta t$:

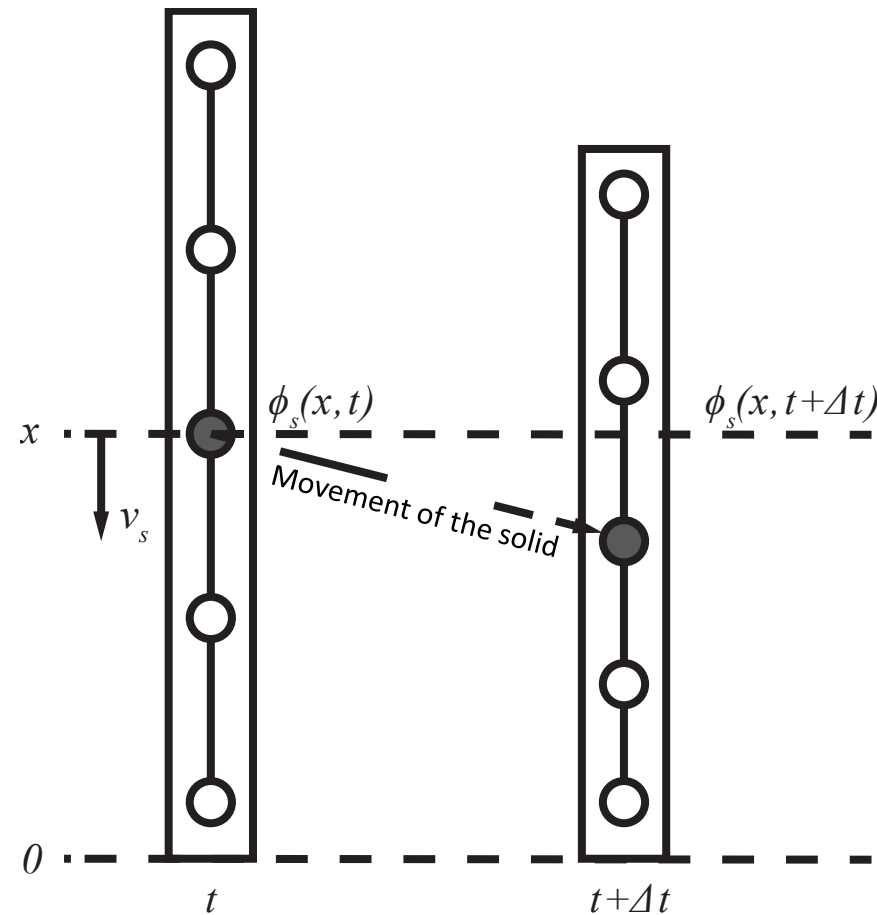


Non-advective assumption

Full equations

Identical wet & dry
compaction behaviour

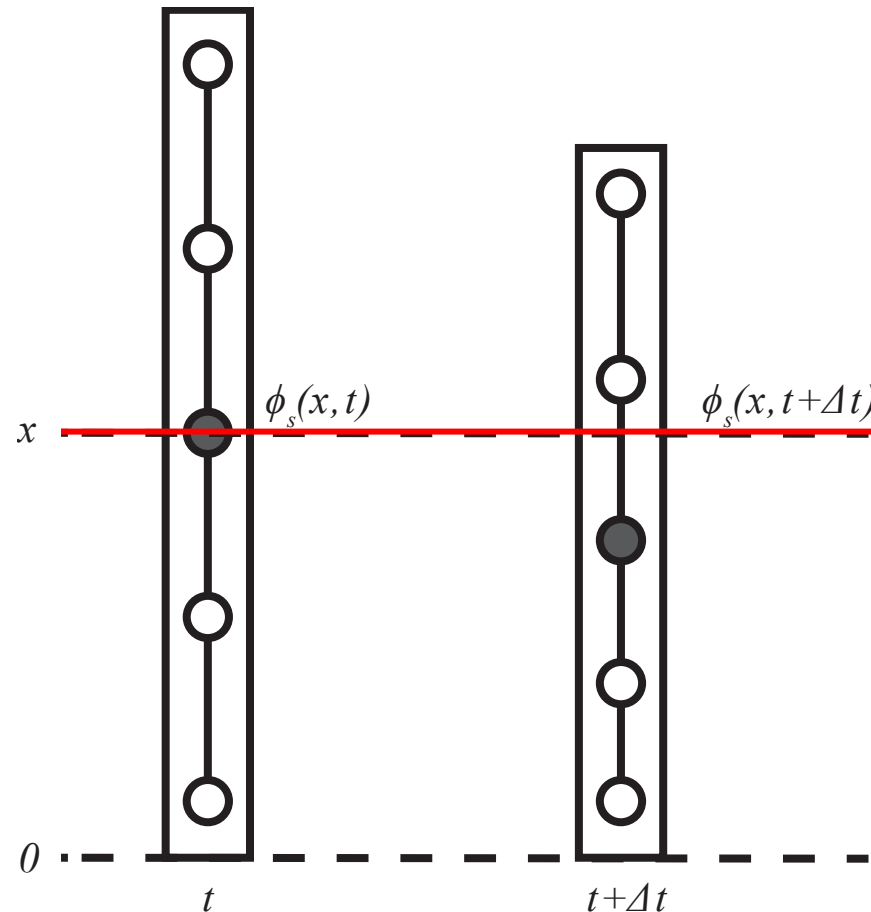
Non-lubricative



material time derivative
= local + advective

- Assume negligible advection (assume that the movement of the solid v_s is negligible)

material time derivative
= local + advective



$$\frac{\partial}{\partial x} \left(\frac{K(\phi_s)}{\mu} \frac{\partial p}{\partial x} \right) = - \frac{1}{\phi_s} \frac{\partial \phi_s}{\partial t}$$

Full equations

Identical wet & dry
compaction behaviour

Non-lubricative

Neglect change in ϕ_s
in time due to movement
of the fabric

Non-advective

- Large deformations

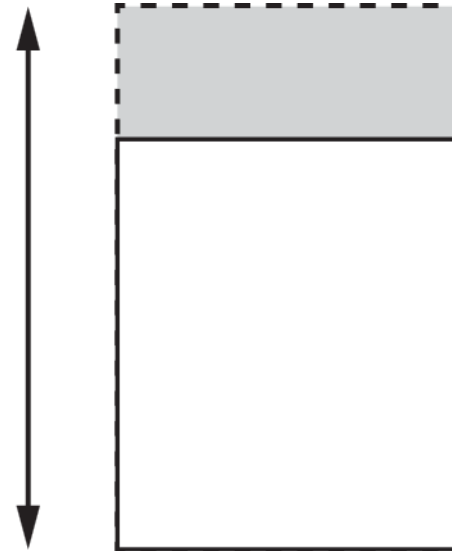
$$\nabla \cdot \mathbf{v}_s = -\frac{1}{dV} \frac{d(dV)}{dt}$$

dV : current elementary
volume

In 1D:

$$\frac{\partial v_s}{\partial x} = -\frac{1}{h_{el}} \frac{dh_{el}}{dt}$$

Initial element height $h_{el,0}$



Element

- Assume small deformations

$$\nabla \cdot v_s = - \frac{1}{dV_0} \frac{d(\Delta V)}{dt}$$

dV_0 : initial elementary
volume

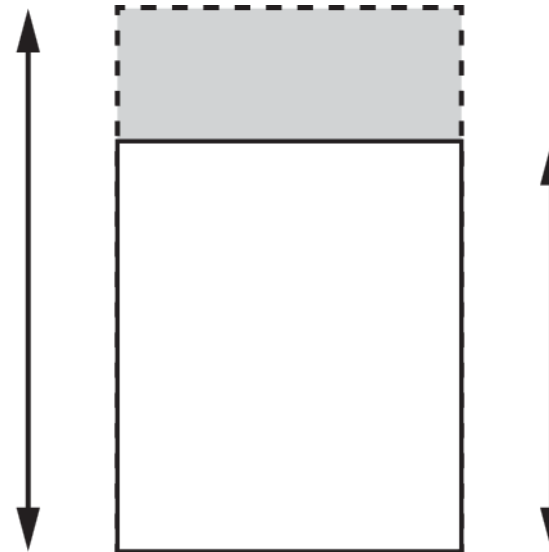
$\Delta V = dV_0 - dV$: change in
elementary volume

In 1D:

$$\frac{\partial v_s}{\partial x} = - \frac{1}{h_{el,0}} \frac{dh_{el}}{dt}$$

Small strain

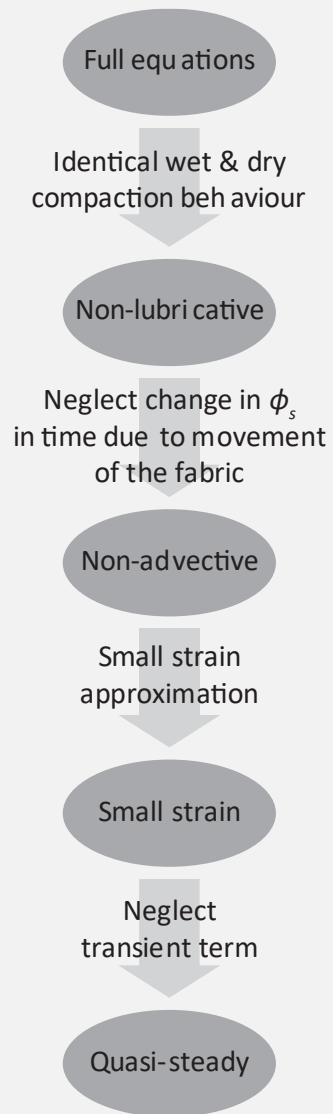
Initial element height $h_{el,0}$



Element

Current element height h_{el}

$$\frac{\partial}{\partial x} \left(\frac{K(\phi_s)}{\mu} \frac{\partial p}{\partial x} \right) = - \frac{\phi_0}{\phi_s^2} \frac{\partial \phi_s}{\partial t}$$

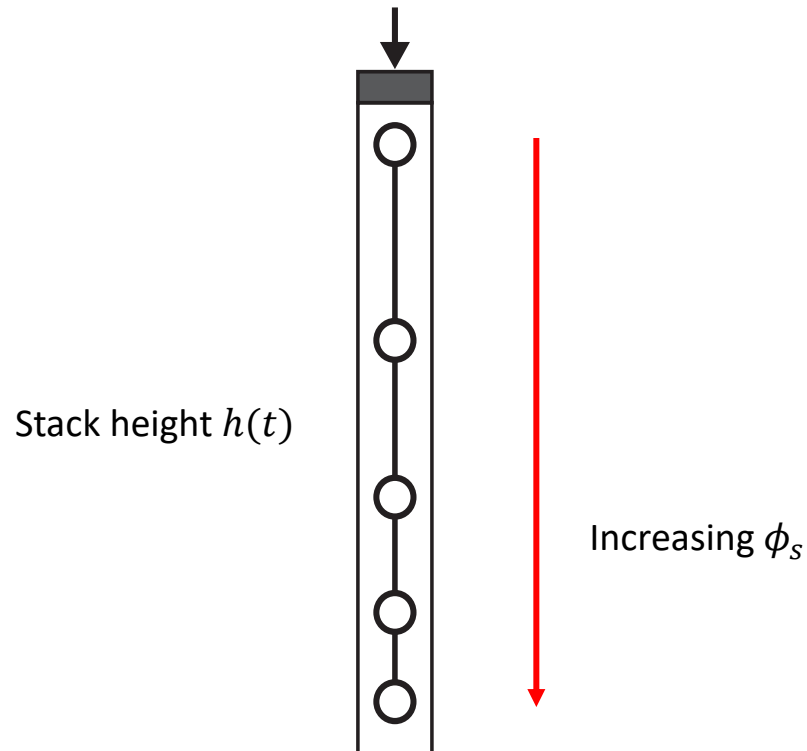


- Assume that flow and deformation are sufficiently slow and solve to steady state at each time step by neglecting the transient term, $\frac{\partial \phi_s}{\partial t} \rightarrow 0$

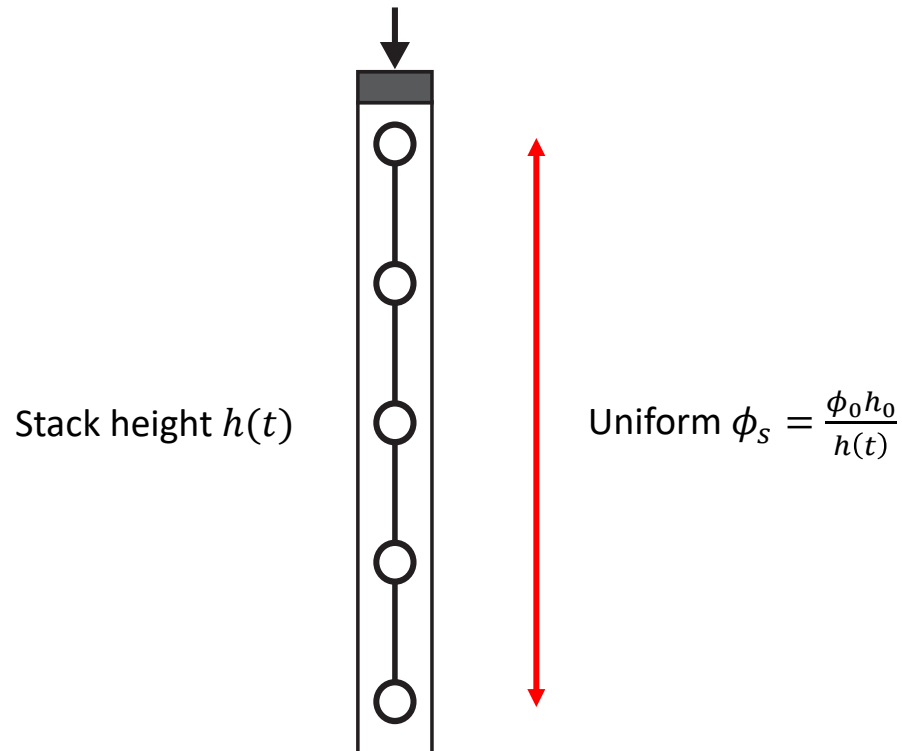
As the flow and deformation become very slow (time derivatives approach zero), solutions should converge

$$\frac{\partial}{\partial x} \left(\frac{K(\phi_s)}{\mu} \frac{\partial p}{\partial x} \right) = 0$$

- Due to hydrodynamic compaction, the nodes are non-uniformly distributed through the thickness for saturated fabric



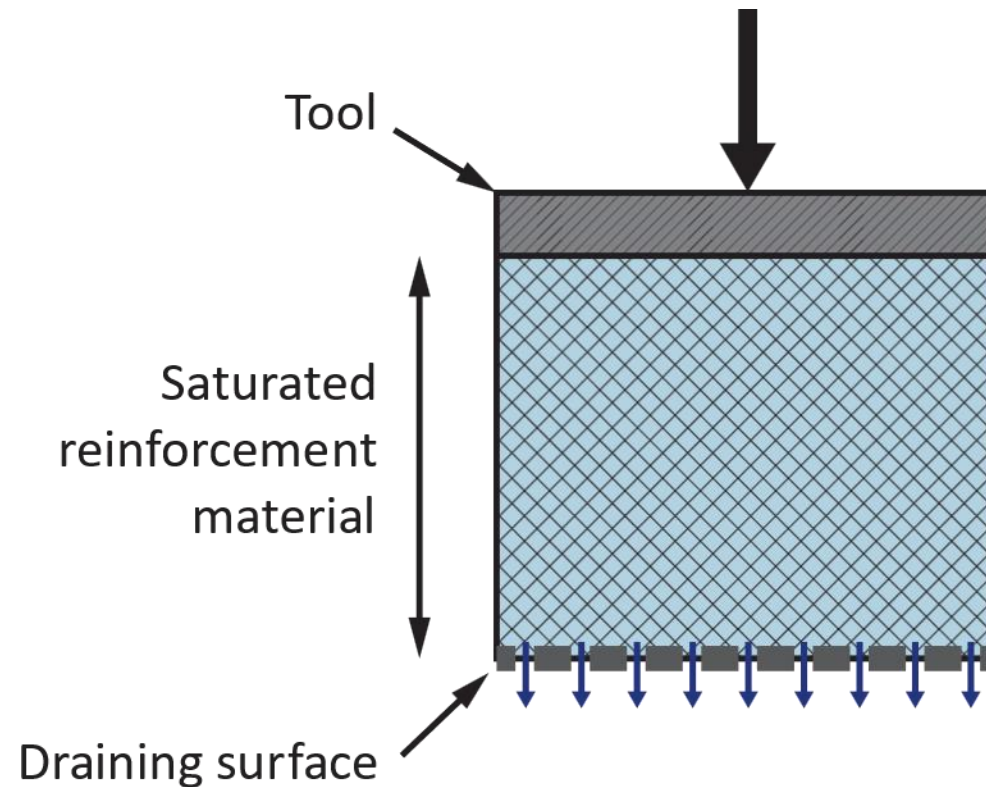
- Assume the distribution of fibre volume fraction is homogeneous through the thickness



$$\frac{K(\phi_s)}{\mu} \frac{\partial^2 p}{\partial x^2} = -\frac{1}{h} \frac{\partial h}{\partial t}$$

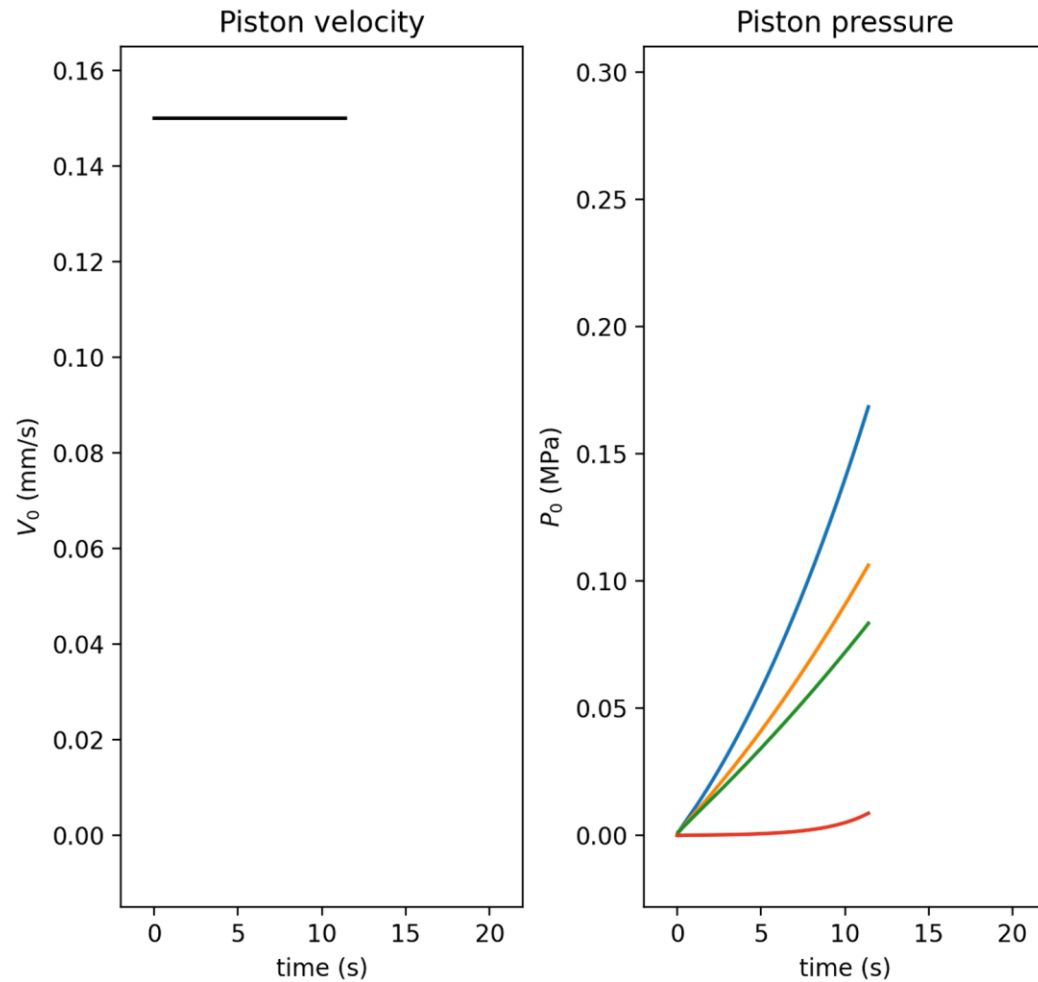
Comparison of simulation results from different process models

- Simplest scenario involving transverse flow and compaction
- Occurs during consolidation of prepreg plies, last stage of most transverse LCM processes when the preform is held at constant thickness/pressure

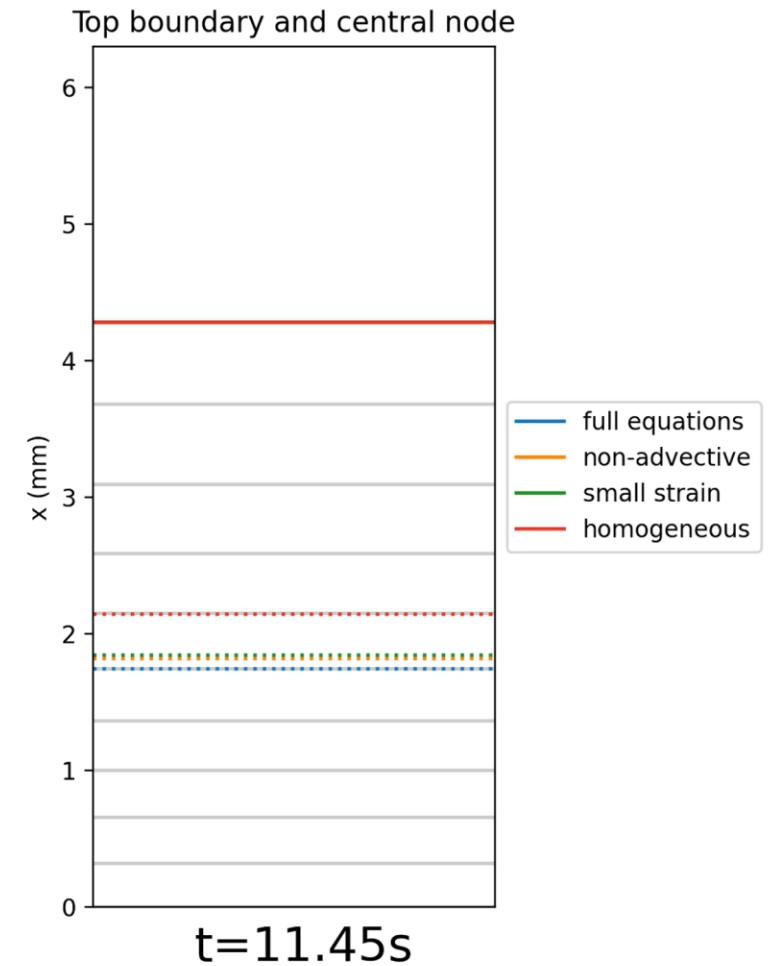


Compression of a saturated stack

Constant compaction velocity



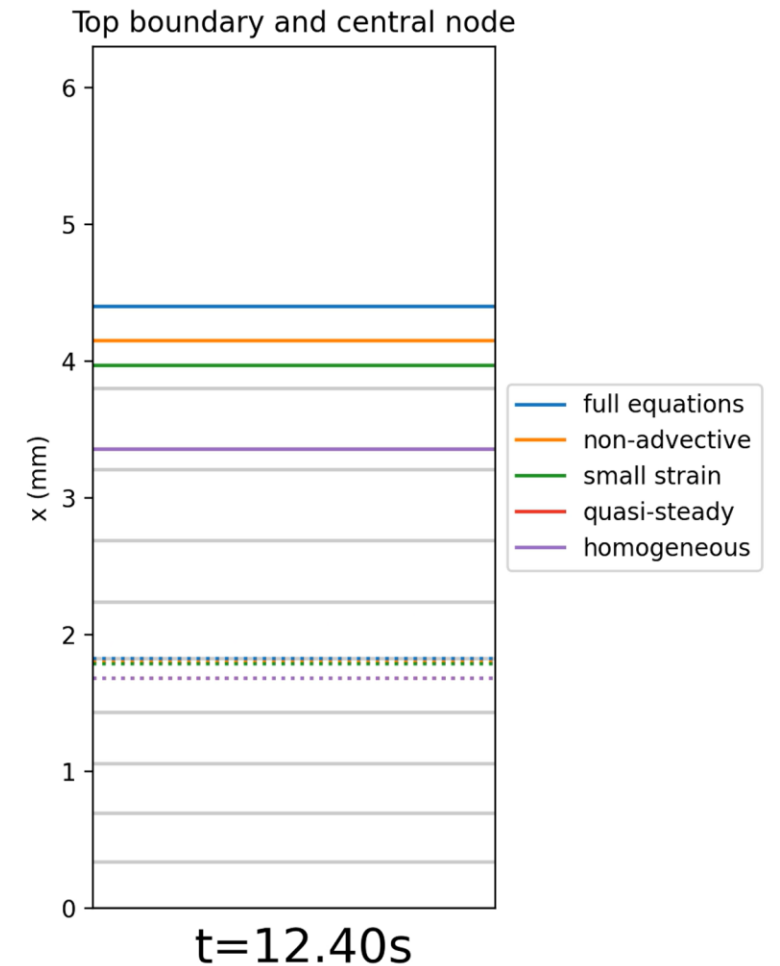
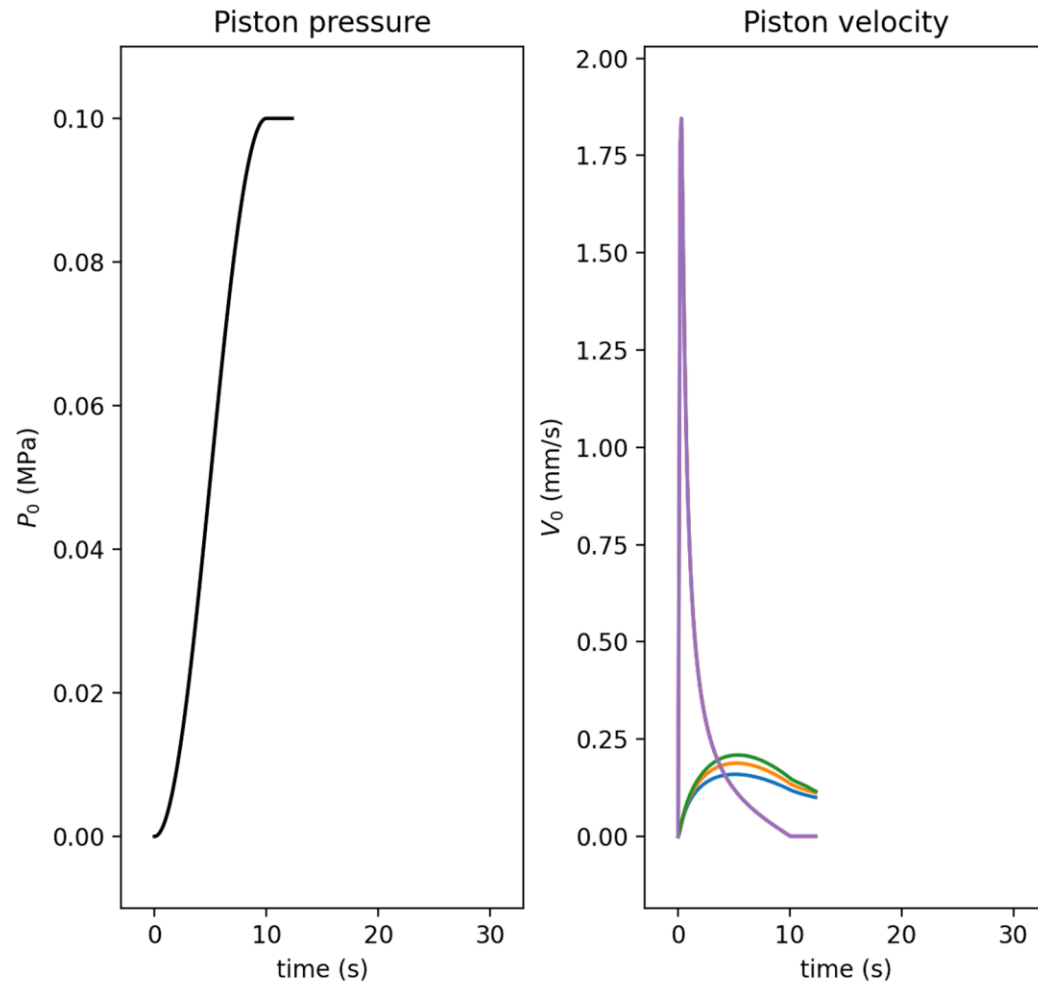
Grey lines represent
elements in the full model



Compression of a saturated stack

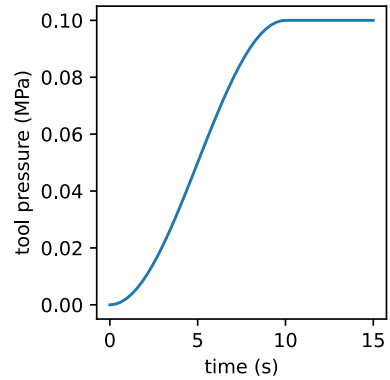
Ramp-up to constant compaction pressure

Grey lines represent
elements in the full model

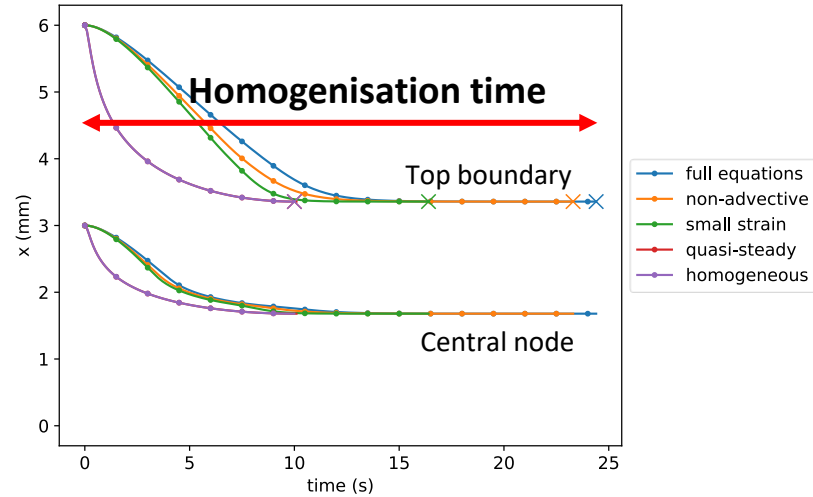


Compression of a saturated stack

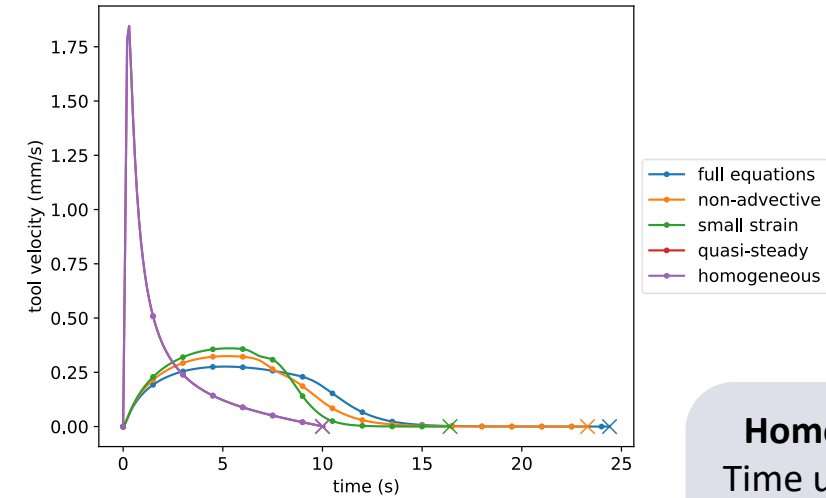
Tool pressure



Node positions



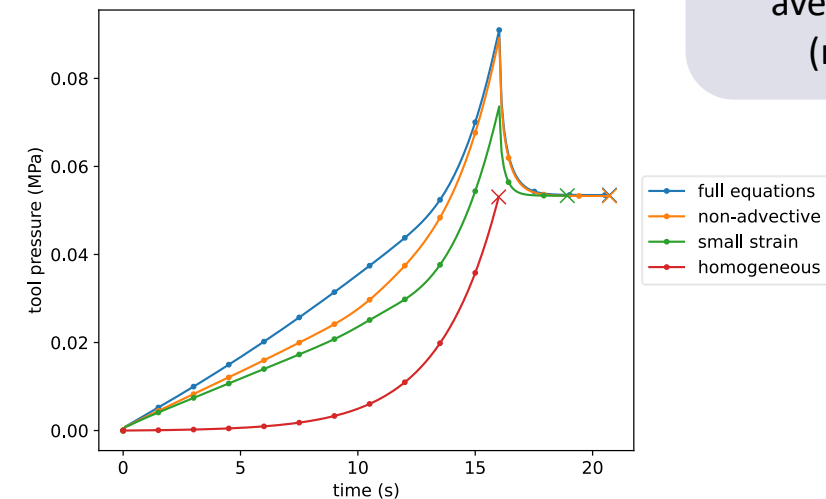
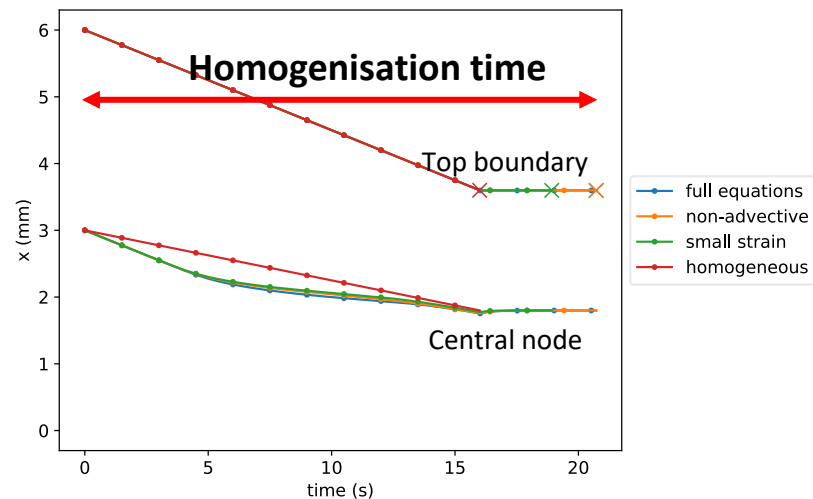
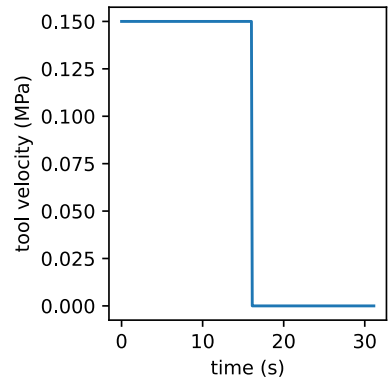
Resulting tool velocity/pressure



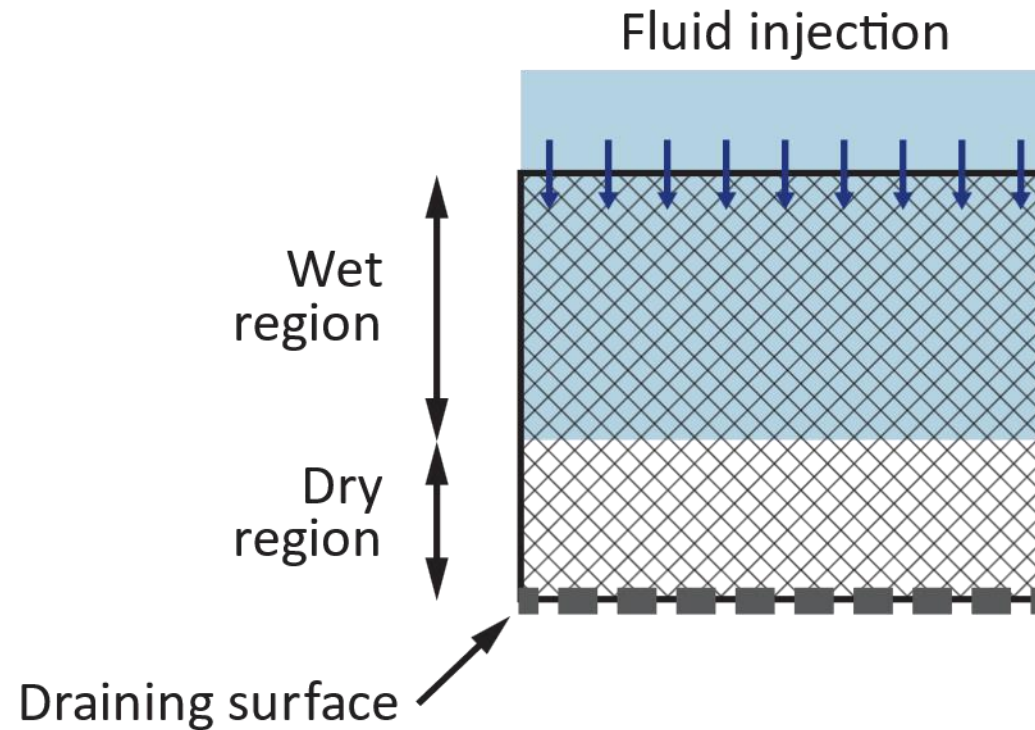
Simulation inputs:
6mm stack of NCF
Viscosity 0.1 Pa.s
100 elements

Homogenisation time:
Time until ϕ_s of all nodes
are within 10^{-6} from the
average value of ϕ_s
(marked as 'X')

Tool velocity

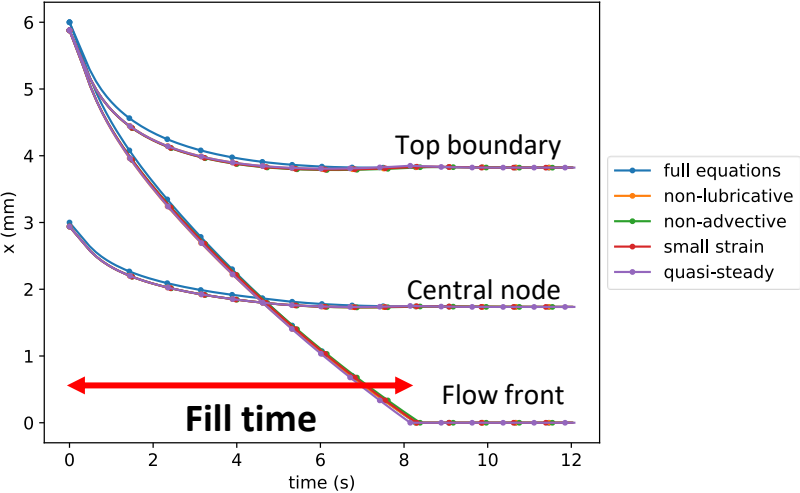


- Injection of fluid at a given flow rate or pressure into a dry preform
- e.g., the first stage of CRTM

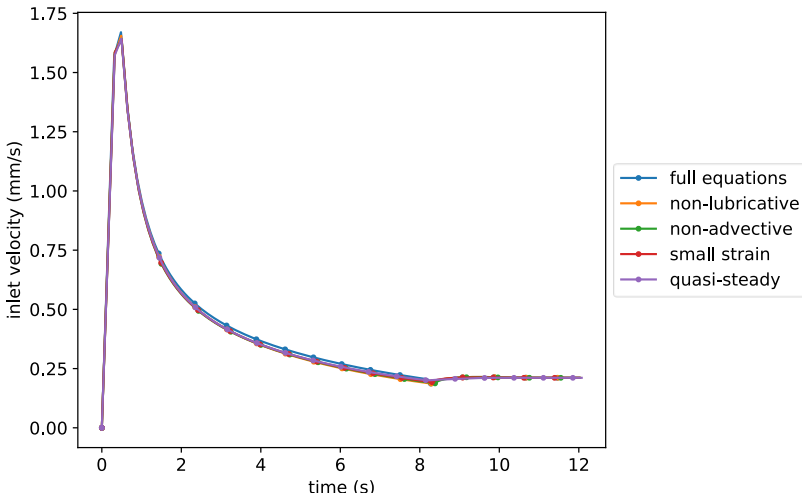


Resin impregnation into a dry stack

Node positions

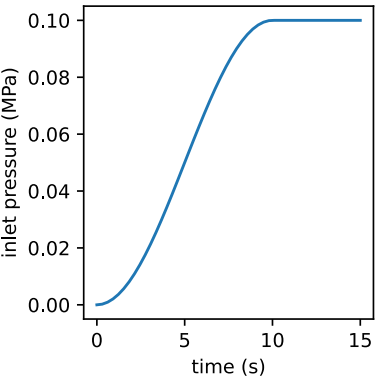


Resulting inlet velocity/pressure

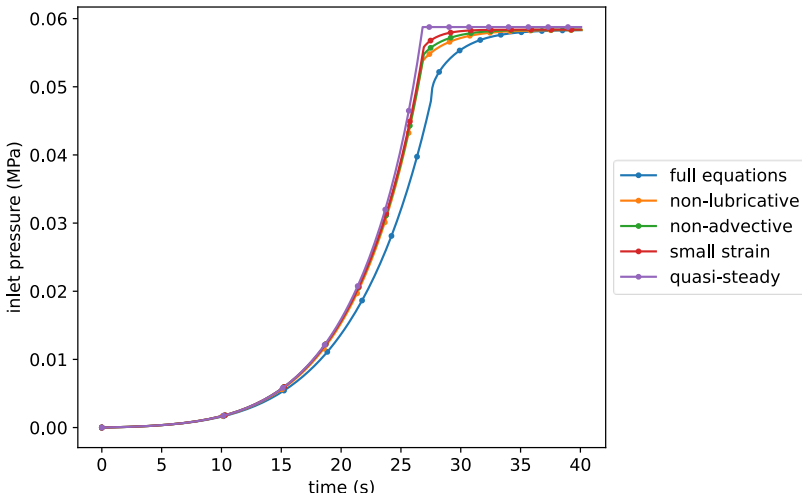
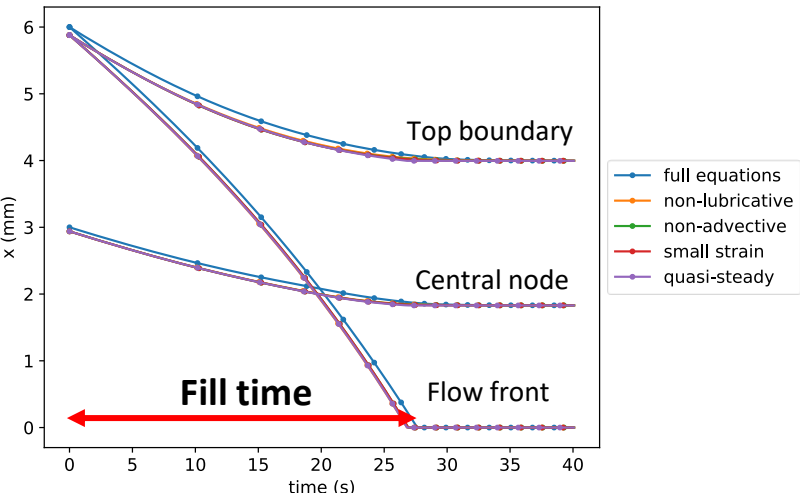
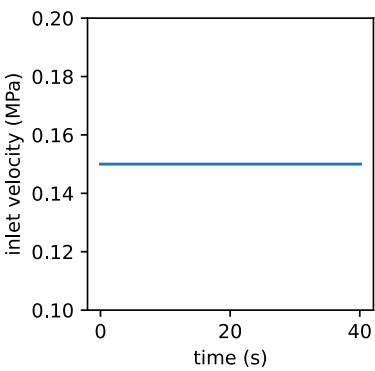


Simulation inputs:
6mm stack of NCF
Viscosity 0.1 Pa.s
100 elements

Inlet pressure

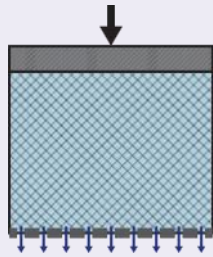


Inlet velocity

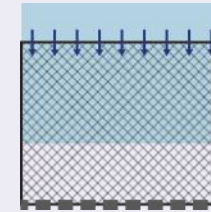


Parametric study

Parametric study: Fluid viscosity



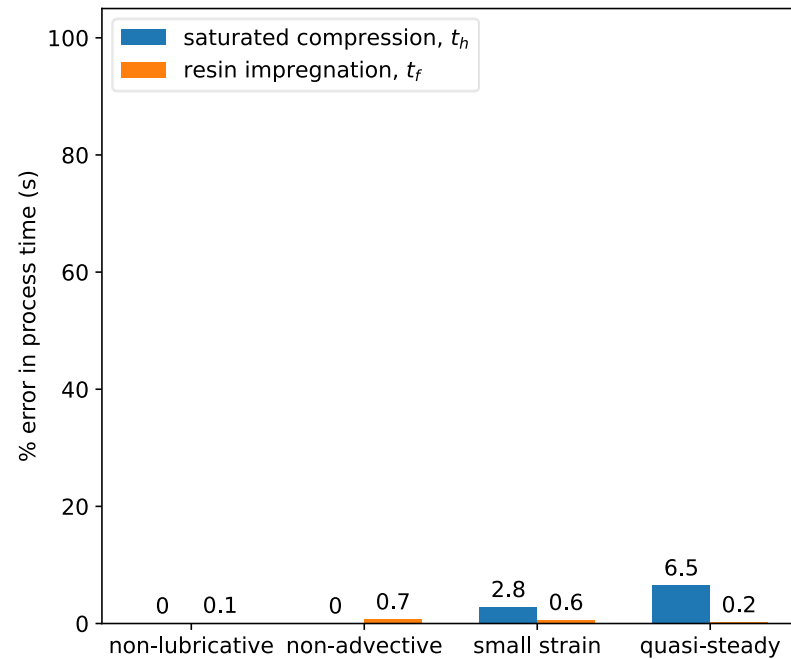
Saturated compression
 t_h : homogenisation time



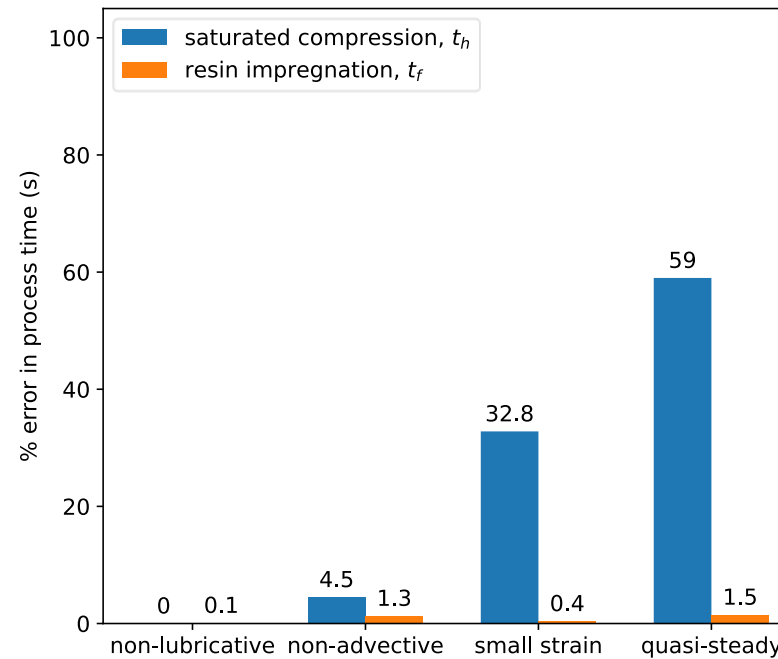
Resin impregnation
 t_f : fill time

Converges with lower viscosity

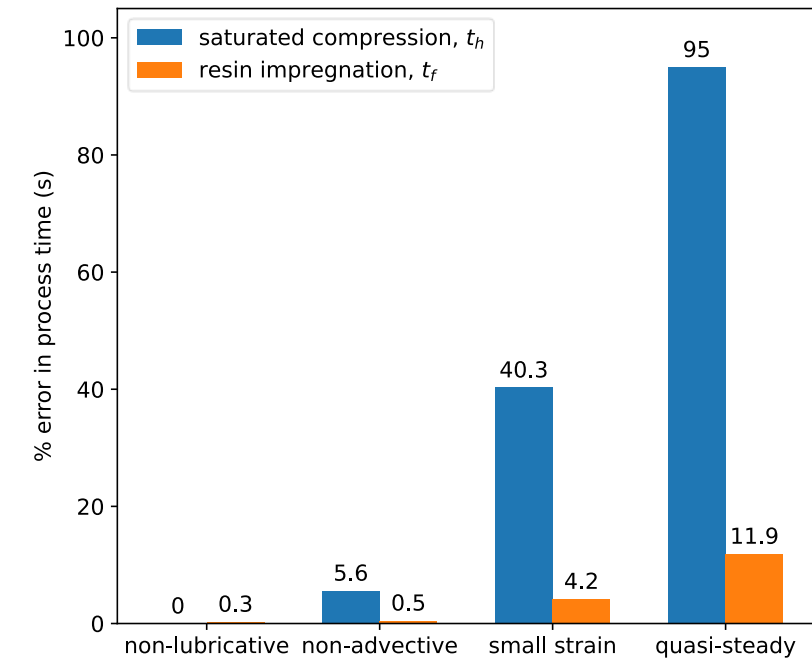
$\mu = 0.01 \text{ Pa.s}$



$\mu = 0.1 \text{ Pa.s}$

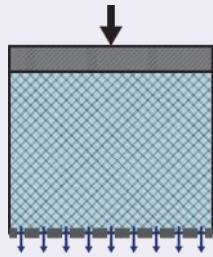


$\mu = 1 \text{ Pa.s}$

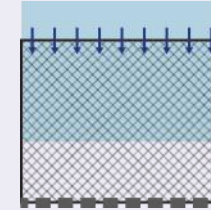


Converges with increasing model complexity

Parametric study: Applied pressure ramp-up



Saturated compression
 t_h : homogenisation time



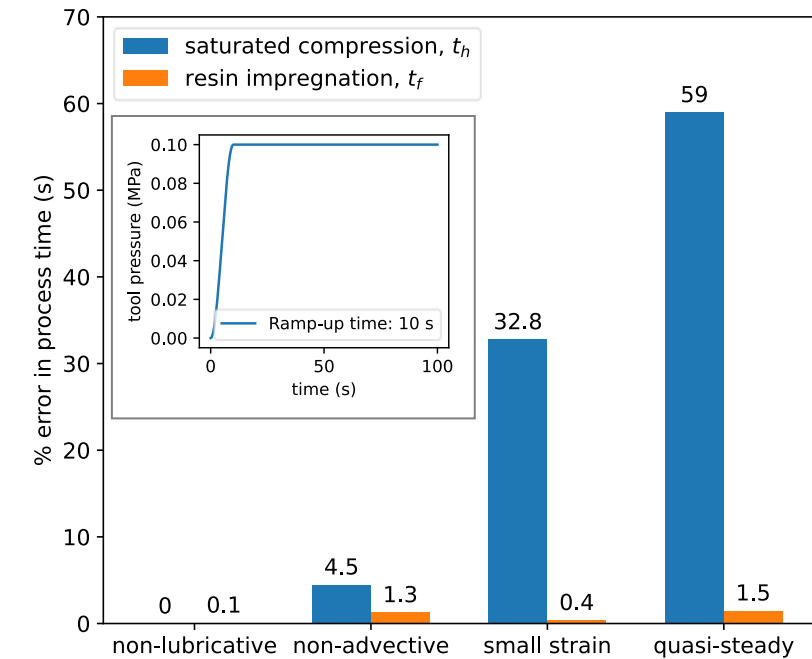
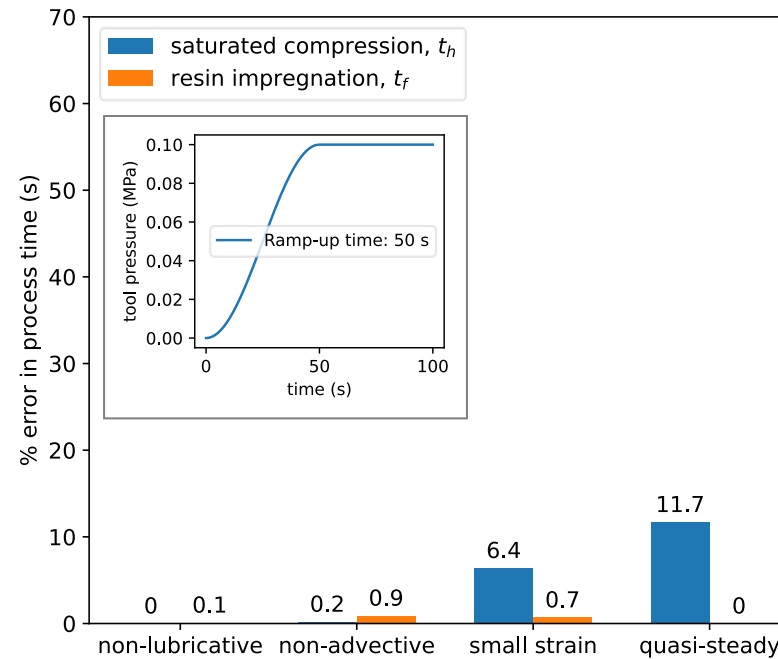
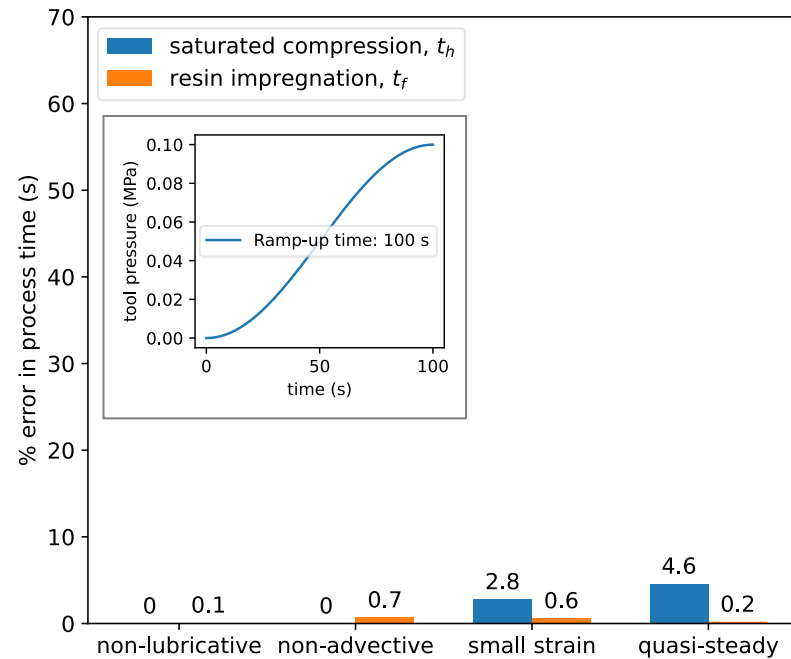
Resin impregnation
 t_f : fill time

Converges with slower flow/deformation

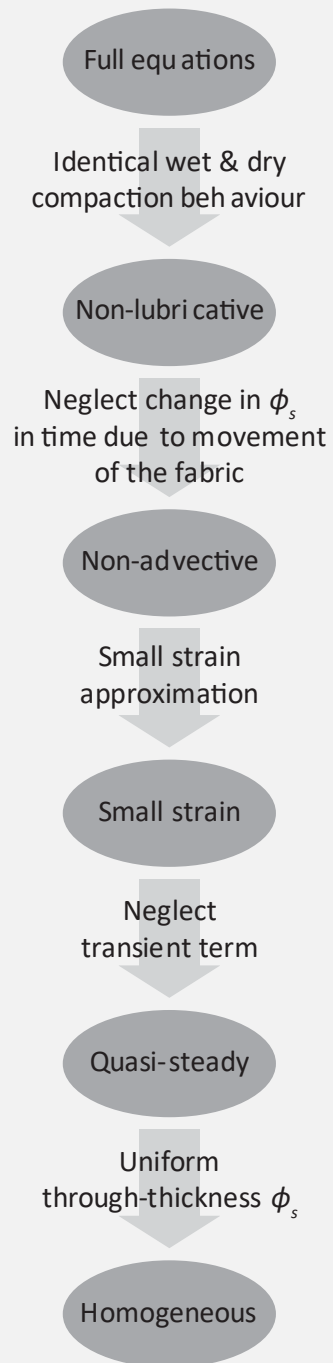
Ramp-up time = 100 s

Ramp-up time = 50 s

Ramp-up time = 10 s



Converges with increasing model complexity

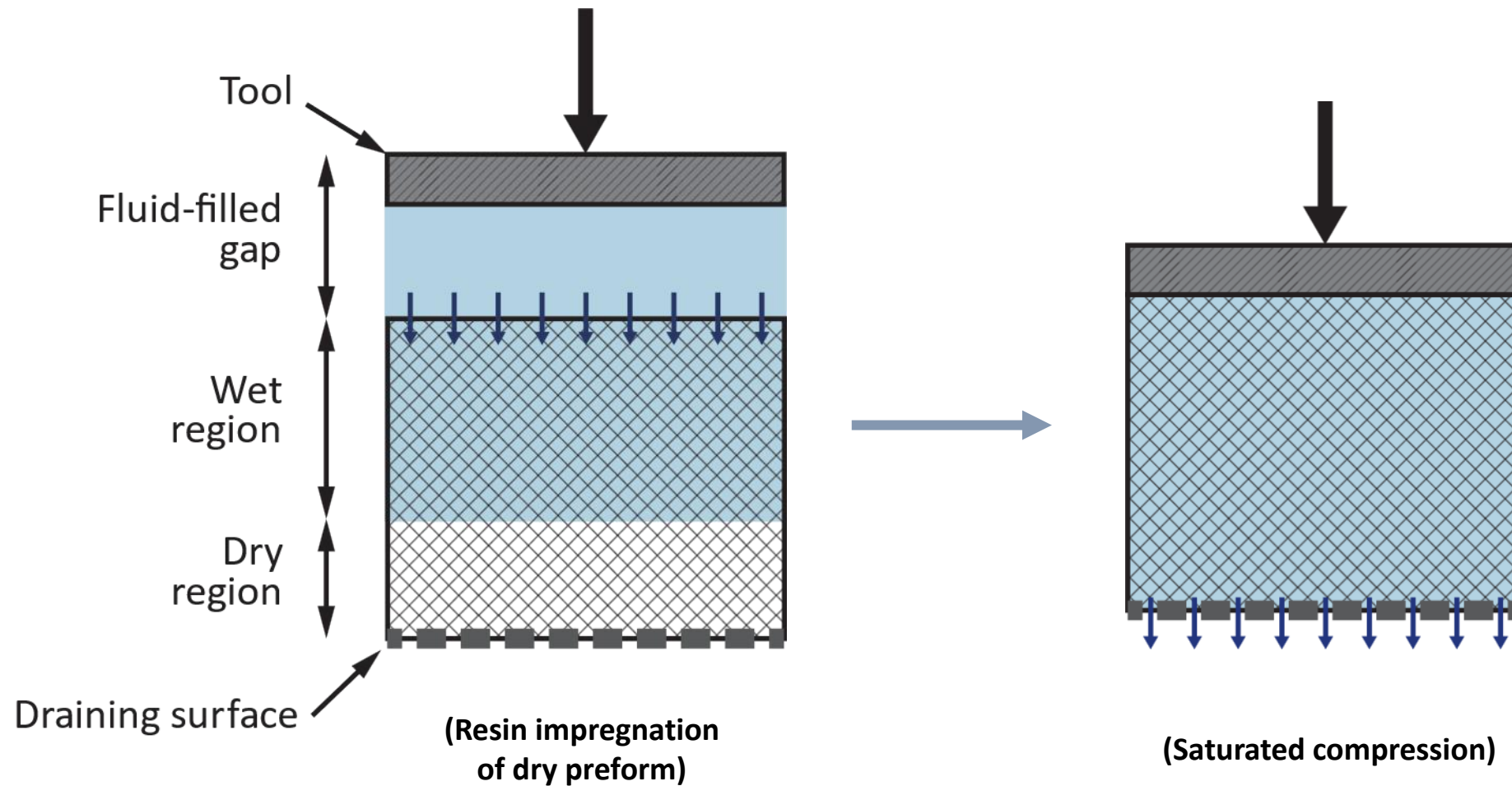


Increasing
error with
decreasing
model
complexity

- Large errors when **tool is in direct contact** with preform, with decreasing error with model complexity
- Smaller errors when top surface is a **free surface** – flow and deformation are slow, sufficient to assume quasi-steady
- Amount of **hydrodynamic compaction** increases with:
 - Fluid viscosity
 - Tool velocity
 - Stack thickness

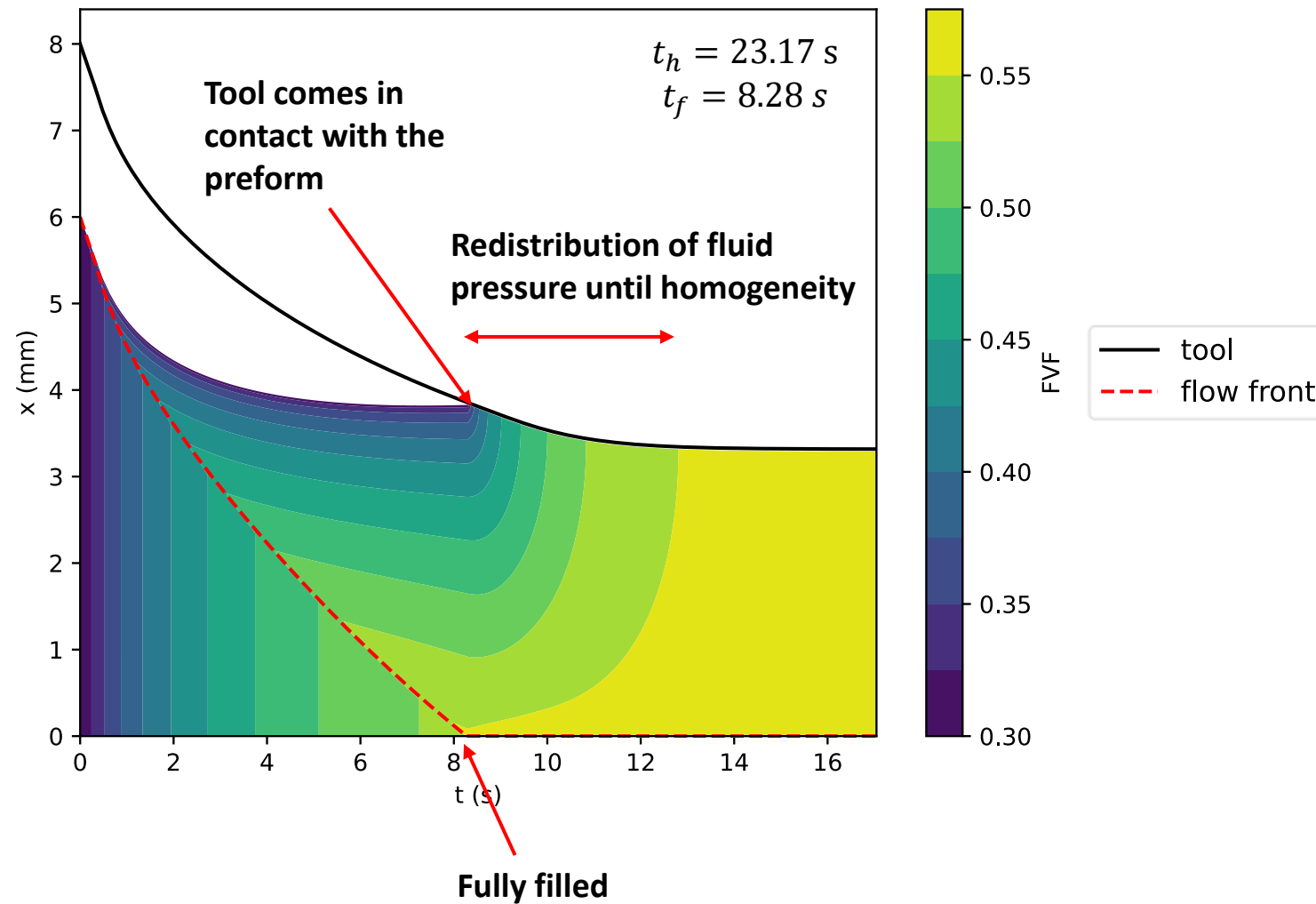
When hydrodynamic compaction effects become significant (increased non-uniformity), the flow and deformation become more non-linear and transient

Compression Resin Transfer Moulding (CRTM)



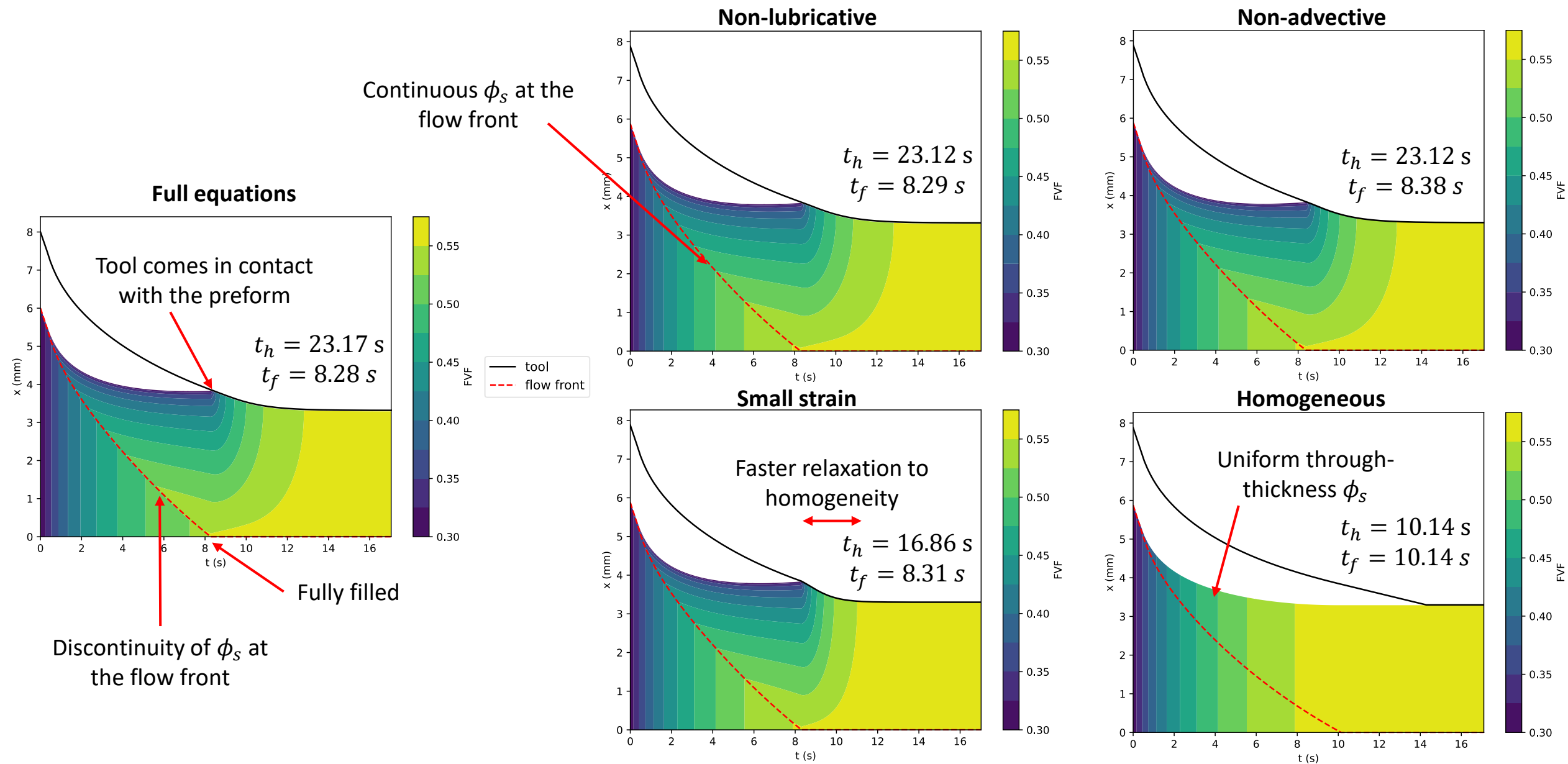
Compression Resin Transfer Moulding (CRTM)

Fibre volume fraction contours



Compression Resin Transfer Moulding (CRTM)

Comparison of fibre volume fraction contours



- **Fully coupled, transient** governing equations are required when simulating processes with **direct piston contact** for accurate predictions
- The transient term is negligible during filling - simple **resin injection** can be modelled with a **quasi-steady** model
- Errors in process time increase with amount of hydrodynamic compaction for the simplified models

Based on content recently published in Composites: Part A

Lee J, Duhovic M, Allen T, Kelly P. Computational modelling and analysis of transverse Liquid Composite Moulding processes. Comp A 2023;167:107433

Thank you



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